Servo | AC Drive | PLC | Motor | Robotic | IOT | Renewable Energy







Part I Marketing H₃U High Performance Small PLC

PMT Eric Weng Dec,2016 Version 1.0



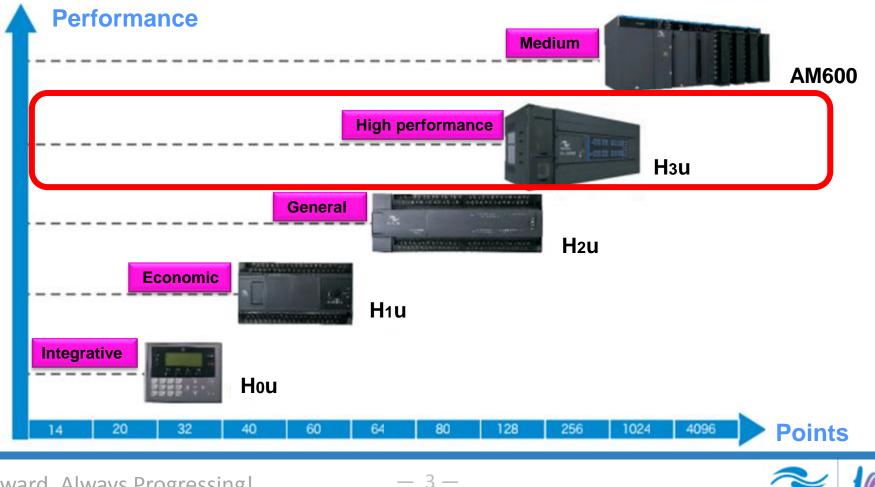
PART 1	Product Overview
PART 2	Hau Highlight
PART 3	System Application





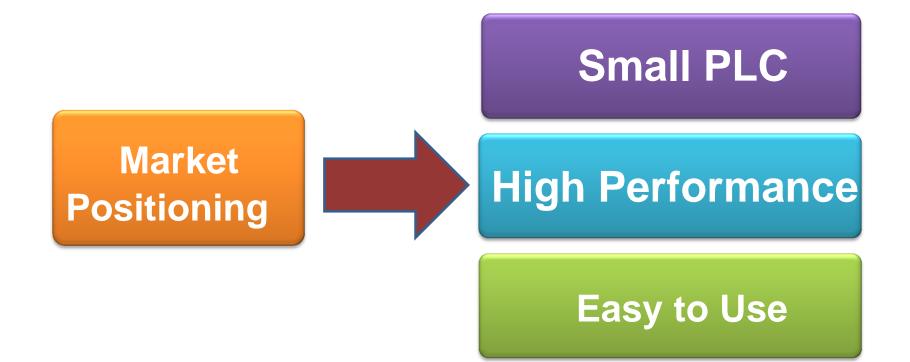
Product Overview PART 1

Market Positioning



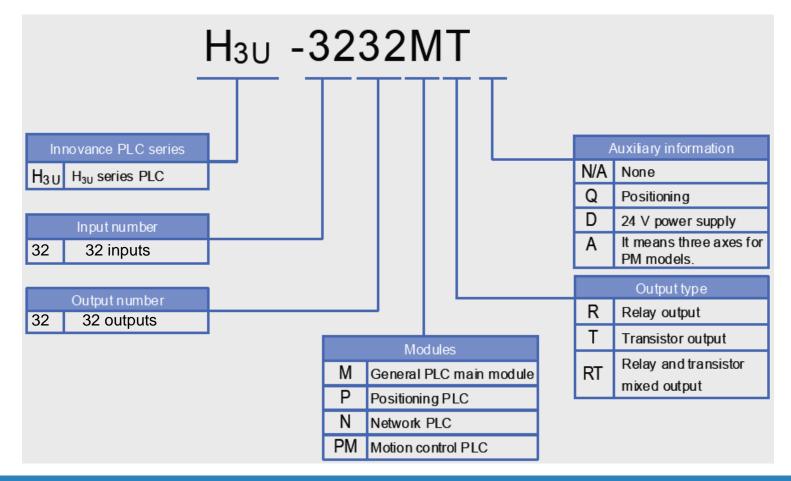
Inovance may Monarch

Market Positioning





Nameplate and Designation Rule





Specifications

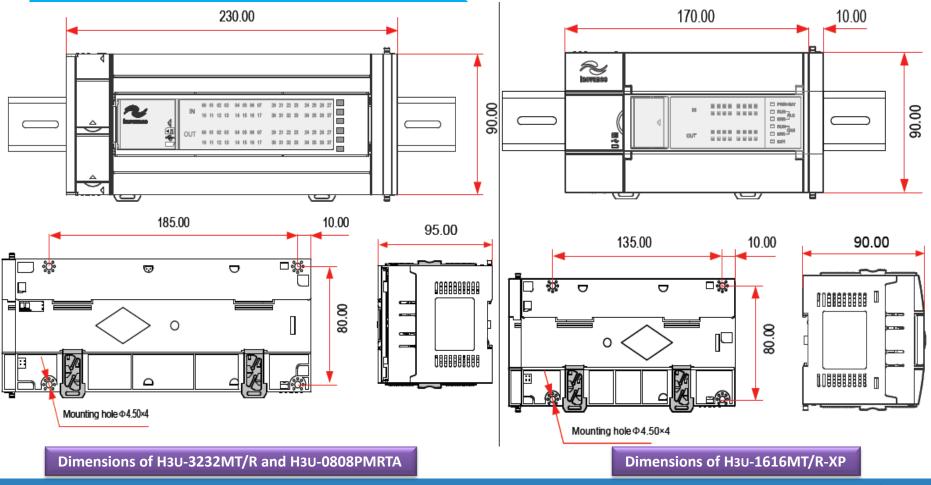
	PLC Model		H3U-1616MT-XP ^[6]	H3U-1616MR-XP ^[6]	H3U-3232MT ^[6]	H3U-3232MR ^[6]	H3U-0808PMRTA ^[5]
	Dimension	Height Width Depth	[W]	: 90 mm : 170 mm : 90 mm		[H] : 90 mm [W] : 230 mm [D] : 95 mm	
	Power Supply			10	0~240VAC(+10% / -15	5%)	
rated uts	Total input	s	16	16	32	32	8 ^[1]
Integrated Inputs	High-speed in	puts	8x200kHz	8x200kHz	8x200kHz	8x200kHz	3x200kHz ^[2]
_	Total outpu	ts	16	16	32	32	8 ^[3]
Integrated Outputs	High-speed out	tputs	5x200kHz	N/A	5x200kHz	N/A	3x500kHz ^[4]
Integ	Output Typ	e	Transistor(NPN)	Relay	Transistor(NPN)	Relay	4 x Relay 4 x Transistor(NPN)
	Serial Port	:		COM0(RS422/RS	5485), COM1(RS485), MC	DDBUS-RTU, DB9	
t Port	CAN Port				CANopen/CANlink		
In-built Port	Ethernet Po	rt			MODBUS-TCP, RJ45		
_	USB(Device	2)			Mini-B		



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Dimensions (unit : mm)



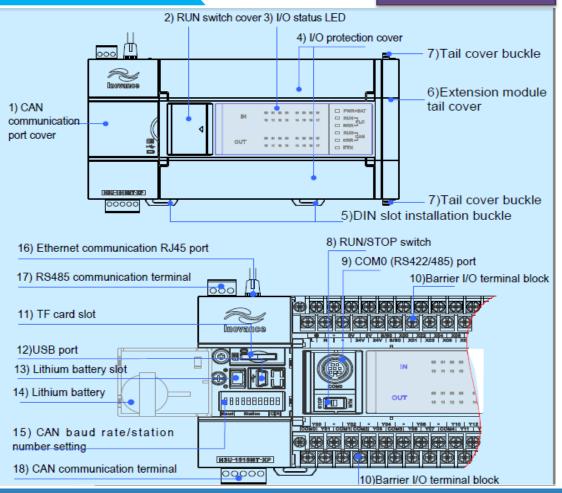
Forward, Always Progressing!

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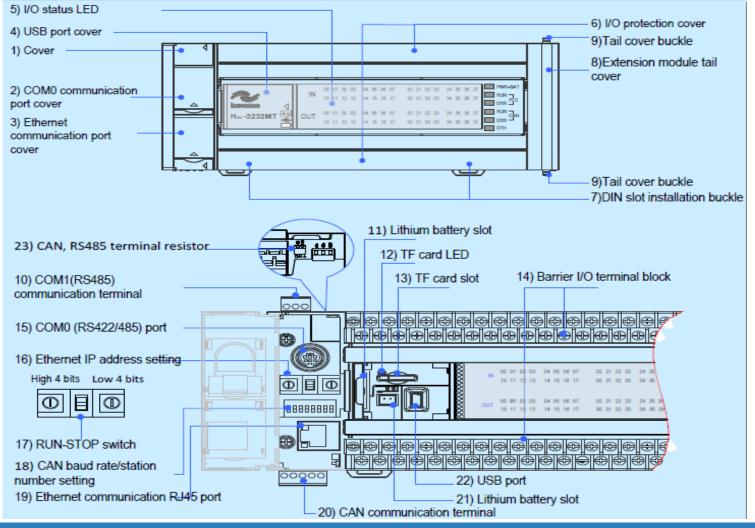
Terminals Configuration

H3U-1616MT/R-XP



Inovance

H3U-3232MT/R or H3U-0808PMRTA





Forward, Always Progressing!

Terminals of H3U-3232MT/R

		50 C	IV C	v)	K00	X02	X04	X06	X1	o x	12 X	(14)	(16	X20	X22	2 X	24	(26	X30	X32	X34	X	86 S/	/S1
L	N	•	24V	24V	X 01	1 X0)3 X()5 X	07	X11	X13	X15	X1	7 X	21	X23	X25	X27	′ X3	31 X	33	X35	X37	

	Y 0	0 Y	02	Y03	Y04	YC)5 Y	06	COM5	Y11	Y1	13 Y	′14	Y16	CON	17 Y	21	′23	Y24	Y26	Y3	0 Y	32	Y34	Y36	CO	M9
C	OM0	Y01	СОМ	1 COI	M2 C(ОМЗ	COM4	Y0)7 Y1	10 Y	'12	COM	5 Y15	5 Y	17	Y20	Y22	CON	18 Y2	25 1	(27	Y31	Y33	3 Y;	35	Y37	

Terminals of H3U-0808PMRTA

		0	v s	/S0 S	TOP0 I	LSP0	PG0-	S/S1	STOF	P1 LSI	P1 P	G1- S	/82 8	TOP2	LSP2	PG	2- 8	8/83	X01	X03	X)5	X07	•
L	N	•	24V	STAR	T0 DOG	0 LSN	NO PG	0+ STA	RT1	DOG1	LSN1	PG1+	STAR	r2 do	G2 l	LSN2	PG2+	X00	0 X	02	X04	X06		•

	A0)+	B0+	A1+	B1	+ A	2+	B2+	CLR0+	FP0+	RP	0+ CLI	R1+ FI	P1+ F	RP1+	CLR2+	FP2	2+ RI	P2+	Y00	Y02		•	Y04	Y06	•
A	10-	B0-	A	1-	B1-	A2-	B2	- CLI	R0- FF	90- F	RP0-	CLR1-	FP1-	RP1-	CLF	2- F	P2-	RP2-	CON	40 Y	01	Y03	COM	1 Y0	5 Y0)7



Terminals of H3U-1616MT/R-XP

		•	0V	0	v	S/\$	50	x	00	X02	×	04	X	06	x	10	X 1	2 >	(14	x	16	S/S1
L	N	•	24	4∨	24	4∨	S/S	50	X	01 ;	< 03	×	05	х	07	x	11	X 13	×	15	X 1	7

	Y	00	•	Y	02	•	• Y	04	•	, ,	Y06		•	Y 1	10	Y1:	2	•	Y	14	Y	16	•	•
со	мо	Y01	со	M1	co	M2	Y03	co	МЗ	Y05	Y	07	со	M4	Y1	1	Y13	СС	DM5	Y	15	Y17	,	



Terminals Configuration

Function	Terminals of st	andard models	Terminals of motion control models
Function	H _{3U} -3232MT/R	H _{3U} -1616MT/R-XP	H _{3U} -0808PMRTA
Power input	L, N	I, PE	L, N, PE
Power output	24\/	4, 0∨	24V, 0V
Normal transistor NPN output	Y05~Y37	Y05~Y17	Y00~Y03
High-speed transistor NPN output	Y00~Y04	Y00~Y04	-
Relay output	Y00~Y37	Y00~Y17	Y04~Y07
High-speed differential output		-	FPx+, FPx-, RPx+, RPx
Normal transistor zero-clearing NPN output		-	CLRx+, CLRx- (CLRx-common terminal)
Normal input	X10~X37	X10~X17	STOPx, LSPx, LSNx, DOGx, STARTx
High-speed input	X00~X07	X00~X07	-
High-speed differential input		-	Ax+, Ax-, Bx+, Bx-, PGx+ and PGx-, leakage-type and source-type input



Models

Model	Туре	Order code
H _{3U} -0808PMRTA	H _{3U} motion controller main module – 16-point transistor relay mixed output	01440001
Н _{зU} -1616МТ-ХР	H _{3U} standard main module – 32-point transistor output	01440021
H _{3U} -1616MR-XP	H _{3U} standard main module – 32-point relay output	01440022
H _{3U} -3232MT	H _{3U} standard main module – 64-point transistor output	01440015
H ₃₀ -3232MR	H _{3U} standard main module – 64-point relay output	01440020
AM600-1600END	16-channel digital input module	01440005
AM600-0016ETN	16-channels transistor output module (NPN)	01440018
AM600-0016ER	16-channels relay output module	01440017
AM600-0016ETP	16-channels transistor output module (PNP)	01440003
AM600-4AD	4-channel analog input module	01440006
AM600-4DA	4-channel analog output module	01440007
AM600-RTU-COP	CANopen communication module	01440011
AM600-PS2	Power supply module	01440010
AM600-4PT	4-channel input thermal resistance temperature detection module	01440008 (under development)
AM600-4TC	4-channel input thermo-couple temperature detection module	01440009 (under development)



Global Design Standards

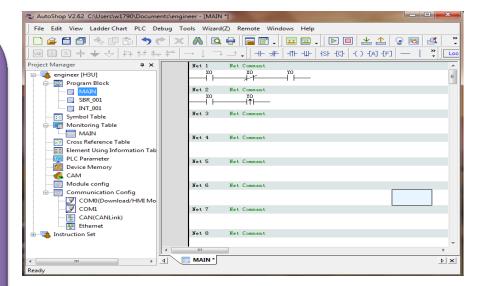


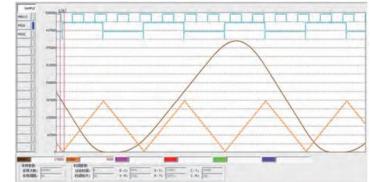




PC-Based Software

- PC-based software-AutoShop can achieve the PLC programming, parameters upload, download, real-time oscilloscope and other functions.
- Programming language: ladder、instruction list、SFC
 Operating in Win7\WinXP







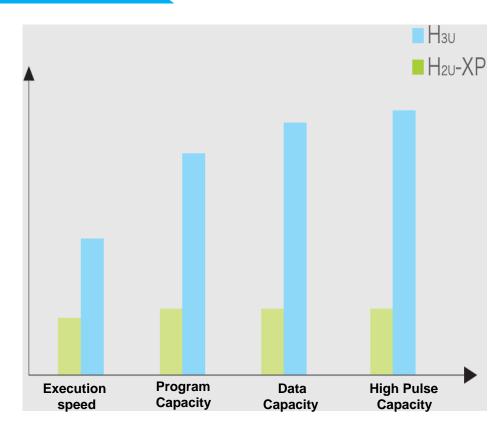


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PART 2	H3U Highlight
PART 3	System Application



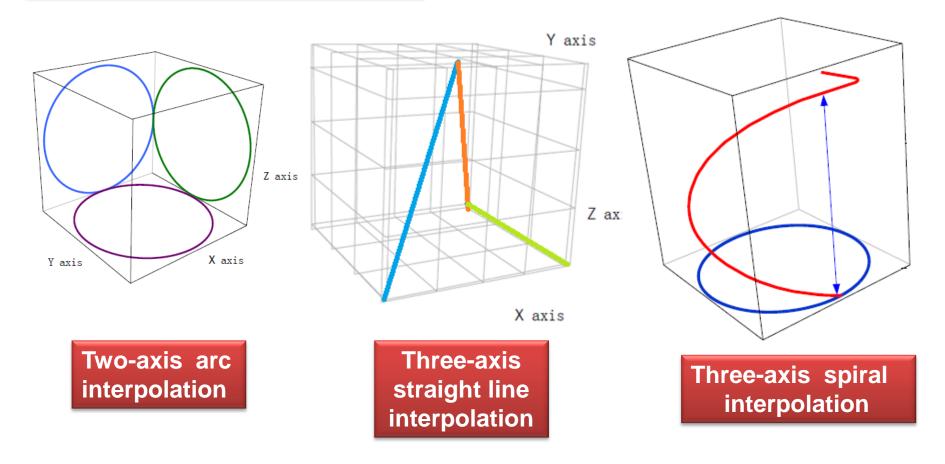
High Performance and large Capacity

- □ All-in-one CPU, power supply and I/O
- Basic instruction:100ns/instruction
- □ Program capacity: 64K steps
- Device memory Auxiliary Relays 9216 points Timers 512 points Counters 256 points Data Registers 9552 points File Registers 32768 points
- □ High-speed inputs: 200kHz
- High-speed outputs:
 200kHz(Standard Model)
 500kHz(Motion Control Model)





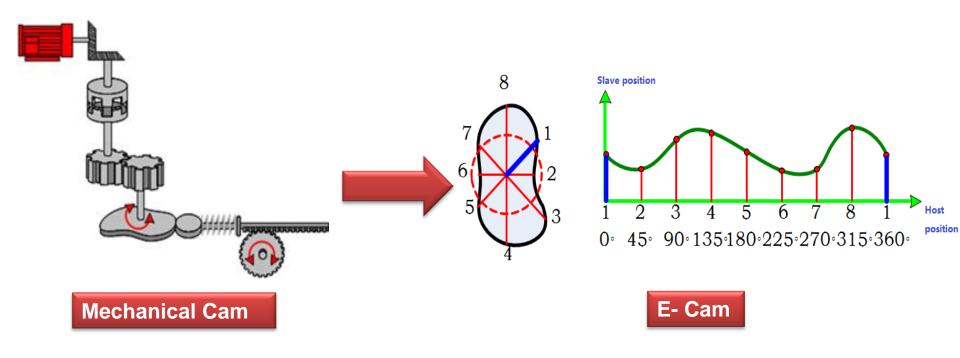
Powerful Motion Control





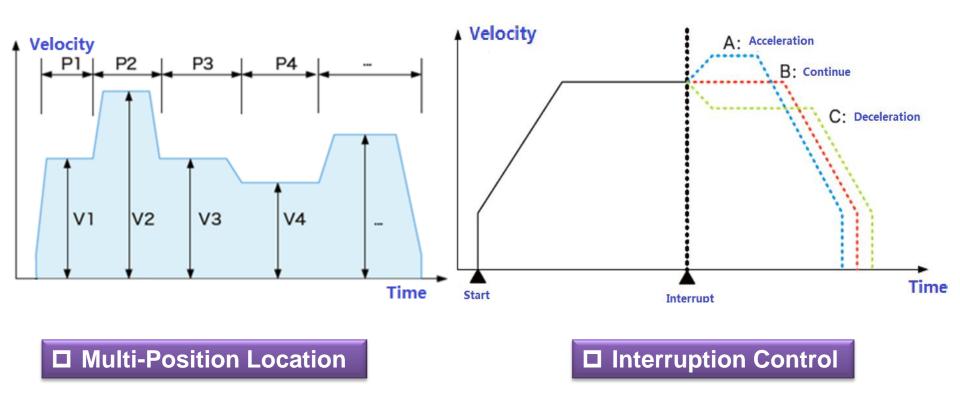
Powerful Motion Control

Three-axis electronic cam replaces the mechanical cam, more flexible and low cost



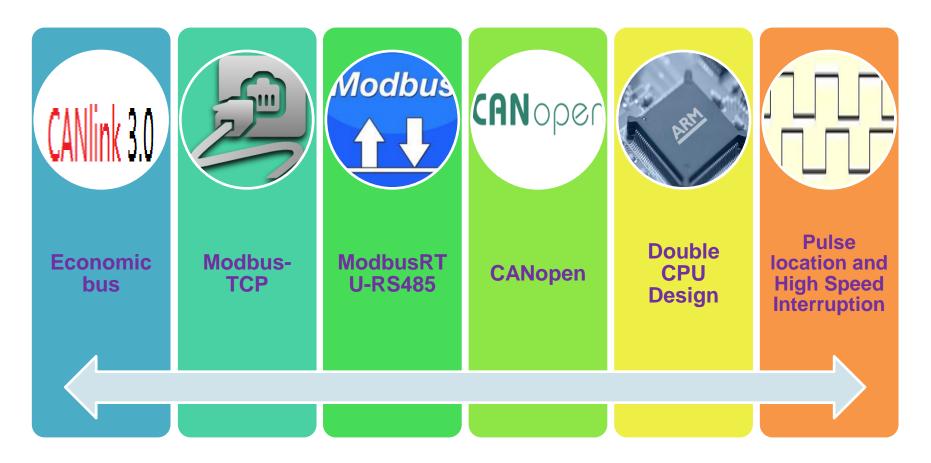


Powerful Motion Control





Rich Network Solution





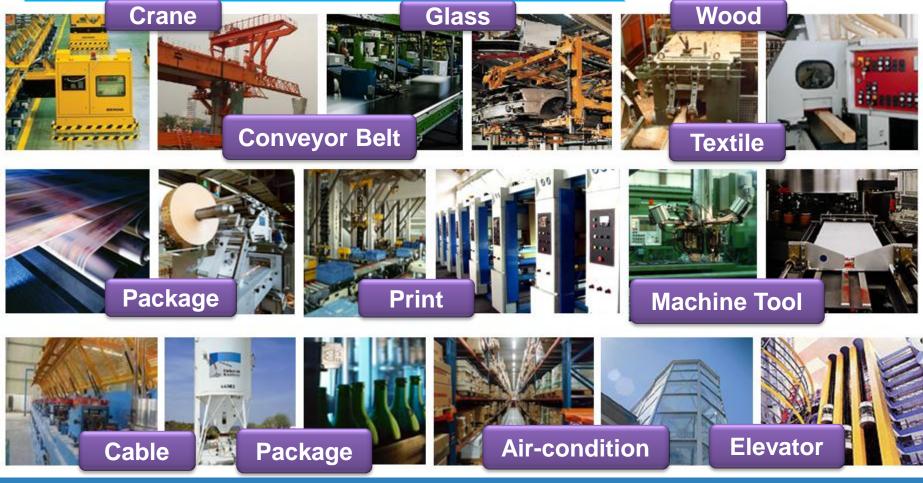


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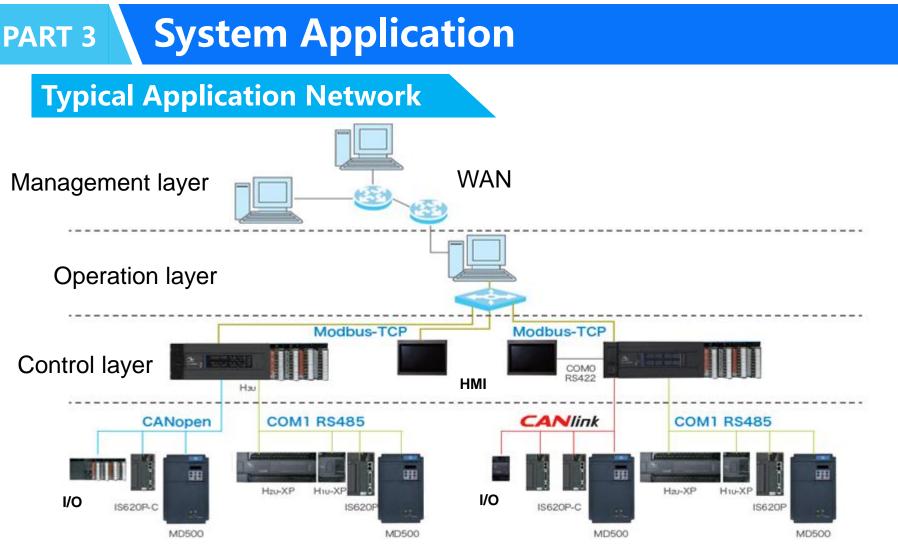
PART 3 System Application

Application Industry









Execution layer



PART 3 System Application

Application In Machine Feeding

The scheme realizes machine feeding system, using path planning function of H3u to achieve trajectory planning, logical planning

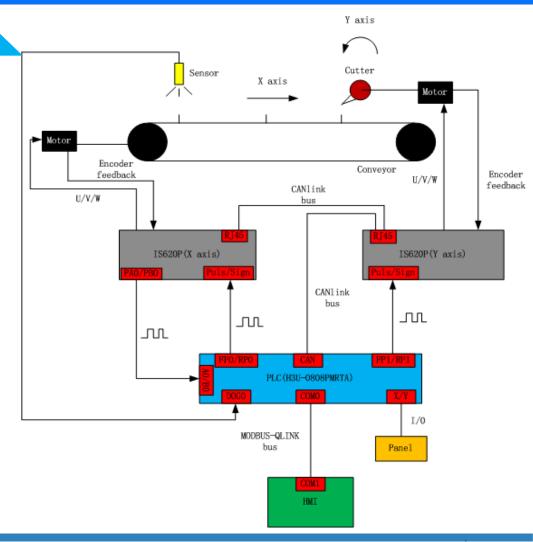




PART 3 System Application

Application In Rotary Cutting

H3u controls the X axis to drive the conveyor to feed the material, controls the Y axis to drive the cutter to circle, counts the pulses output by X axis to calculate the on-going convey distance. E-CAM function of H3u describes the running distance relationship between the X and Y axis.





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